AMENDMENTS TO THE SPECIFICATION:

Kindly replace the paragraph beginning at page 5, line26, with the following amended paragraph:

Each actuator FT, RT (hereinafter represented as FT) includes a motor M and a reduction mechanism RD, respectively. FIG. 3 is an example of the actuator FT. In the first embodiment, a three-phase brushless motor is used as the motor M. Although configuration of the motor M is ~~not only limited to~~ <u>shown as</u> the three-phase brushless motor, ~~but also~~ another type of motor (for example, common motor including brush, and another phase number) may be used.

Kindly replace the paragraph beginning at page 6, line 1, with the following amended paragraph:

Accordingly, in the stabilizer <u>control unit</u> ECU1, target value of active roll moment is set for each front and rear wheel based on vehicle active roll moment set value and front/rear wheel roll torsion modulus set value for active control of vehicle roll moment. According to this target value of active roll moment, torsion stress for generating at front (and/or rear) actuator FT (and/or RT) is determined. Then, the motor is activated [[in]] <u>and</u> controlled to reach the determined torsion stress. By making active work to control the torsion force to each stabilizer bar 31, 32 with the actuator FT, vehicle roll can be reduced or inhibited when the vehicle is driven. ~~Although~~ <u>The</u> control method of the stabilizer is not [[only]] limited to the embodiment described, but [[also]] another method (for example the method described in the

disclosed Japanese Patent Laid-open Publication No. 2002-518245, cited above) may be used.

Kindly replace the paragraph beginning at page 8, line 15, with the following amended paragraph:

In addition, a rotation detection [[mean]] <u>means</u> 40 for detecting rotation of the stabilizer bar 31 is disposed in the housing 1. Although the rotation detection [[mean]] <u>means</u> 40 comprises at least one magnet 41 provided along outer circumferential of the rotor 12 and at least one hall IC 42 disposed at interior of the housing 1 in the present embodiment, another type of the rotation detection [[mean]] <u>means</u> (for example, optical rotary encoder) may be used.